

# Global Existence and Uniqueness of a Field Modelling the Thermal State of Three-dimensional Superconductor ( $1 \leq N \leq 3$ )

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In this paper, we will study the global existence of a thermic field modelling the physical state of a three - dimensional superconductor. The superconductor is considered as a widely bounded regular field, with the usual physical data.

Key words: Nonlinear, existence, monotonous operator, supraconductors.

## I. Study framework

The thermic state of a superconductor field  $\Omega$ , is given by the following mathematic model: [1], [5], [6], [7], [10], [11], [12], [13] and [15]:

$$c(x, t) = \frac{\partial u}{\partial t} - \sum_{i,j=1}^N \frac{\partial}{\partial x_j} [k_{i,j}(x, t) \frac{\partial x_i}{\partial t}] =$$

$$\lambda F(u) + P \text{ in } \Omega \times \mathbb{R}^+ \quad (1)$$

$$\frac{u}{\partial \Omega \times \mathbb{R}^+} = 0 \quad (2)$$

$$\frac{u}{\partial \Omega \times \{0\}} = u_0 \quad (3)$$

With:

- $c$  : Specific heat of material.
- $k_{ij}$  : Components of the thermic conductivity tensor.
- $F$  : Non linearity term, representing the source of energy.
- $P$  : Thermic perturbation .
- $\lambda$  : Assembling parameter of all intensive amounts of the problem.

### 0.1.1 Functional framework

Functional framework, describing our study, is based on the mathematic reading of physics data. [12], [14], and [16]

For an initial data  $u_0 \in C^0(\Omega)$ , finding a solution  $u(t; \cdot)$  in the space

$$E = C(\mathbb{R}^+, C^0(\Omega) \cap C^1(\mathbb{R}^+, H_0^1(\Omega))) \cap C^1(\mathbb{R}^+, L^2(\Omega))$$

From a physical point of view, the components of

the tensor of thermic conductivity, for the spacial variable  $x$ , are continuous, strictly positive functions, and in a lower temperatures, strictly increasing. This, suppositions are mathematically modelised by the following assumption  $H_k$ :

For all  $i$  and  $j$ :

-  $k_{ij}$  is strictly positive and increasing of  $C^1(\Omega \times \mathbb{R}^+)$ . There are two constants independent of  $x$  and  $t$   $k_1$  and  $k_2$  such as

$$k_1 < k_{i,j}(x, t) < k_2 \text{ for all } x \in \Omega \text{ and } t > 0$$

- For all  $1 \leq i \leq N$ , the  $k_{ij}$  are bounded; i-e there is  $M > 0$  such as:

$$\left| \frac{\partial k_{i,j}}{\partial x_i}(x, t) \right| \leq M \text{ for all } x \in \Omega \text{ and } t > 0$$

Specific heat  $c$ , is a continuous strictly positive function for the spacial variable  $x$ , checking  $H_c$ :

-  $c$  is  $C^1(\Omega \times \mathbb{R}^+)$ , strictly positive, and there are two constants independent of  $x$  and  $t$   $c_0$  and  $c_1$  such as:

$$c_0 < c_{i,j}(x, t) < c_1 \text{ for all } x \in \Omega \text{ and } t > 0$$

- There exists  $c_2 > 0$  independent of  $x$  and  $t$  such as:

$$\left| \frac{\partial c}{\partial x_i}(x, t) \right| \leq c_2 \text{ for any } (x, t) \in \Omega \times \mathbb{R}^+$$

$F$  is the term of energetic competition between a power dissipated by Joule effect  $G$ , and that absorbed by the cryogenic bath  $Q$ :

$$F(u) = G(u) - Q(u)$$

The diversity of the techniques carrying out the

superconductive state and maintaining its thermal stability, generates a whole of acceptable classes  $U_{ad}^G$  for the term  $F$ . These classes are characterized primarily, but not only, by the existence of an element  $u_1 > 0$  such as:

$$F(u_1) = 0$$

Let us note, moreover, that all elements of  $U_{ad}^G$  are  $C^2(E)$  and null for the negative values ( $u < 0$ ). These assumptions represent the noted hypothesis  $H_0$ . In a quasi-general way, there are three techniques or systems of cooling ( Helium I, Helium II and the temperature control by the field edges). Each system is modeled by the hypothesis  $H_0$  and only hypothesis  $H_m$  with  $m \in \{1; 2; 3\}$  such as:

- $H_1$ :

there exists  $u_2 > u_1$  such as  $F(u_2) = 0$  and

$F'(u) \leq 0$  for all  $u \geq u_2$

- $H_2$ :

$$\lim_{u \rightarrow \infty} F(u) = F_\infty$$

- $H_3$ :

$\exists \gamma_1 > 0$  such as  $\lim_{u \rightarrow \infty} \left( \frac{F(u)}{u} \right) < \gamma_1$  and

$$\lim_{u \rightarrow \infty} F(u) = +\infty$$

Then, we define classes of this term as follows:

$$U_{ad}^m = \{F \text{ checking } H_0 \text{ } H_m\} \text{ with } 1 \leq m \leq 3$$

Thus, the general class  $U_{ad}^G$  is defined by:

$$U_{ad}^G = \bigcup_{m=1}^3 U_{ad}^m$$

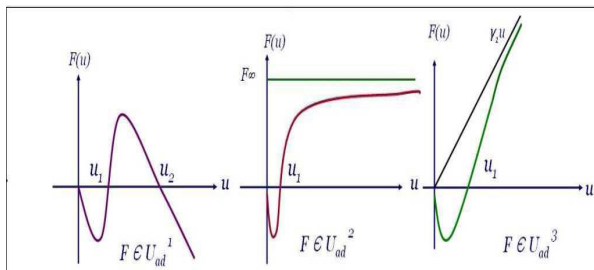
The whole of these assumptions is deduced from nature of experimental curves, given by the various cooling systems.

**Remark 0.1.1** Let us recall that the physical data are obtained for example in [12], [14], and [15]

- $U_{ad}^1$  characterizes cooling system by Helium II .

- $U_{ad}^2$  gives cooling model by extrinities.

- $U_{ad}^3$  characterizes cooling system based on Helium I.



### 0.1.1 Thermic model

For  $c$  and  $k_{ij}$  verifying the hypothesis  $H_c$  and  $H_k$ , and for  $F$  element of  $U_{ad}^G$ , the superconductor thermic state is a  $\bar{u}$  element of  $E$  checking:

$$Pe \begin{cases} c(x,t) \frac{\partial u}{\partial t} - \sum_{i,j=1}^N \frac{\partial}{\partial x_j} [k_{i,j}(x,t) \frac{\partial x_i}{\partial t}] = \lambda F(u) + P \text{ in } \Omega \times IR^+ \\ u / \partial \Omega \times IR^+ = 0 \\ u / \partial \Omega \times \{0\} = u_0 \end{cases}$$

Balance states are solutions of the corresponding elliptic nonlinear problem:

$$\begin{cases} - \sum_{i,j=1}^N \frac{\partial}{\partial x_j} [k_{i,j}(x,0) \frac{\partial u}{\partial x_i}] = \lambda F(u) + P \text{ in } \Omega \times IR^+ \\ u / \partial \Omega = 0 \end{cases}$$

### 0.2 Simply nonlinear case

We remind, here, some results concerning the case of the constant thermophysic coefficients; In fact this case represents the isotropic state. Without loss of generality, we suppose that:

$$c = 1 \text{ and } k = Id$$

The problem becomes:

$$(Pe, 1, Id) \begin{cases} \frac{\partial u}{\partial t} - \Delta u = \lambda F(u) + P \text{ in } \Omega \times IR^+ \\ u / \partial \Omega \times IR^+ = 0 \\ u / \partial \Omega \times \{0\} = u_0 \end{cases}$$

**Lemma 0.2.1** For all  $F$  element of  $U_{ad}$ , we have :

a) There exists two constants  $\alpha$  and  $\beta > 0$  such as:

$$uF(u) \leq \alpha u^2 \text{ for all } |u| \geq \beta$$

b) There exists two constants  $\alpha > 0$  and  $\mu > 0$  such as:

$$F(u) \leq \mu |u| \text{ for all } |u| < \alpha$$

Proof:

a) For  $F \in U_{ad}^2$ ,  $F(u) \leq 0$  for all  $u \geq u_2$

When  $F$  is in  $U_{ad}^1$ ,  $F$  behaves as as constant beside  $+\infty$ .

So there exists  $u_*$  such as:

$$\text{For } u \geq u_* \text{ } F(u) \leq F_\infty$$

We have the lemma for:

$$\beta = \sup(u_*, u_2) \text{ and } \alpha = F_\infty$$

For  $U_{ad}^0$ , there exists  $u_0$ :

$$\text{For } u \geq u_0, uF(u) \leq (F_0 + 1)u^2$$

Is then :  $\alpha = F_0 + 1$  and  $\beta = u_0$

Thus, we can choose for all  $F$  in  $U_{ad}^G$  :

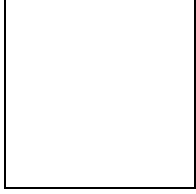
$$\beta = \sup(u_*, u_2, u_0), \alpha = \sup(u_2, F_\infty, F_0 + 1)$$

b) is trivial. It's enough to choose:  $a = u_1$  and  $\mu > 0$ .

**Theorem 0.2.2** For all  $(F; u_0) \in U_{ad}^G \times C_0(\Omega)$ , the problem  $(Pe; 1; Id)$  admits a unique global solution.

The conditions required by the class  $U_{ad}^G$  (continuity of  $F$ , local Lipschitz and  $F(0) = 0$ ) allow to apply the theorem of chapter 5rd of [3]. Which shows the local existence of the solution. Lemma 0:3:1 gives the results of the global existence.

**Proposition 0.2.3** If  $\mu$  is a constant checking:



Then, there exists a constant  $A < \infty$ ,

such as if

$$\|u_0\|_{C^0(\Omega) \cap H_0^1(\Omega)} < u_1 A$$

That:

a) The global solution verifies:

$$\|u_0\|_{C^0(\Omega) \cap H_0^1(\Omega)} \leq A \|u_0\|_{C^*(\Omega) \cap H_0^1(\Omega)} e^{-(\lambda - \mu)t}$$

for all  $t \geq 0$

b) If  $F \in U_{ad}^2$ , then:

$$\|u(., t)\|_{C^0(\Omega) \cap H_0^1(\Omega)} \leq e^{-\lambda t}$$

This result flows from the lemma [0:3:2], the proposition 5:3:7 of [3] and the theorem [0:3:3].

### 0.3 Nonlinear case: $c$ and $k_{ij}$ variable functions

We remind the aim of this paper is to prove, the global existence of solution of the problem. This will be done in two stages: study without term of nonlinearity, and then into the general framework. The basis idea is the ability to construct an operator  $L_t$ , which depends to the suitable proprieties to apply the results of [5] [8] and [9].

#### 0.3.1 Operator depending of time

Because of the specific heat is non null, the equation (1) can be put as:

$$\frac{\partial u}{\partial t} - \frac{1}{c(x, t)} \sum_{i,j=1}^N \frac{\partial u}{\partial x_j} [k_{i,j}(x, t) \frac{\partial u}{\partial x_i}] = \frac{\lambda F(u)}{c(x, t)} + \frac{P}{c(x, t)(4)}$$

If we will note by:  $\tilde{c}$  the inverse of  $c(x; t)$ , we have the new quantities:

$$F_c(u) = \tilde{c} F(u) \quad (5)$$

$$P_c = \tilde{c} P \quad (6)$$

$$D_{ij} = \tilde{c} k_{ij} \quad (7)$$

$$\tilde{D}_{ij} = \tilde{c} \frac{\partial k_{ij}}{\partial x_i} \quad (8)$$

$(Pe)$  will be given by:

$$\frac{\partial u}{\partial t} - \sum_{i,j=1}^N \tilde{D}_{ij} \frac{\partial u}{\partial x_i} - \sum_{i,j=1}^N D_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} =$$

$$\lambda F_e(u) + P_e \text{ in } \Omega \times \mathbb{R}^+ \quad (9)$$

$$u / \partial \Omega \times \mathbb{R}^+ = 0 \quad (10)$$

$$u / \partial \Omega \times \{0\} = u_0 \quad (11)$$

If we introduce the linear operator  $L_t$ :

$$L_t(u) = \sum_{i,j=1}^N (e_{ij} - \tilde{e}_{ij}) \frac{\partial u}{\partial x_i} - \sum_{i,j=1}^N \tilde{e}_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} \quad (12)$$

With:

$$\tilde{e}_{ij} = D_{ij} \quad (13)$$

$$e_{ij} = \frac{\partial D_{ij}}{\partial x_i} - \tilde{D}_{ij} \quad (14)$$

The problem  $(\tilde{Pe})$  is put in the following new form:

$$\frac{\partial u}{\partial t} + L_t(u) = \lambda F_c(u) + P_c \quad (15)$$

We note the spaces:

$$D_{L_t} = L^2(\mathbb{R}^+, H_0^1(\Omega)) \cap C^0(\mathbb{R}^+, L^2(\Omega))$$

and dual space

$$H^{-1}(\Omega) = (H_0^1(\Omega))'$$

**Lemma 0.3.1**  $\tilde{e}_{ij}$  and  $e_{ij}$  are elements of

$$L^\infty(\mathbb{R}^+, L^\infty(\Omega))$$

**Proof :** As the field  $\Omega$  is bounded, and according to assumptions  $Hc$  and  $Hk$ , we have: for

all  $(x; t) \in \Omega \times \mathbb{R}^+$

$$\left| \tilde{e}_{ij}(x, t) \right| \leq \frac{k_2}{c_0} \quad \text{and} \quad \left| e_{ij}(x, t) \right| \leq \frac{2M}{c_0} + \frac{k_2 c_2}{c_0^2} \quad (16)$$

**Proposition 0.3.2** *It is continuous from  $D_{Lt}$  into*

$$L^2(IR^+, H^{-1}(\Omega))$$

Proof:

Let  $v \in H_0^1(\Omega)$  from (12) and (16) we have :

$$\begin{aligned} & \left| \langle L_t(u), v \rangle \right| \leq \sum_{i,j=1}^N \int_{\Omega} \left| e_{ij} \left\| \frac{\partial v}{\partial x_i} \right\| v \right| dx + \\ & \sum_{i,j=1}^N \int_{\Omega} \left| \tilde{e}_{ij} \left\| \frac{\partial v}{\partial x_i} \right\| v \right| dx + \sum_{i,j=1}^N \int_{\Omega} \left| \tilde{e}_{ij} \frac{\partial^2 v}{\partial x_i \partial x_j} v \right| dx \leq \\ & N^2 \sup_{i,j=1}^N \left| e_{ij} \right| \|\Delta u\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} + \\ & N^2 \sup_{i,j=1}^N \left| \tilde{e}_{ij} \right| \|\Delta u\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} + \\ & \sum_{i,j=1}^N \int_{\Omega} \left| \tilde{e}_{ij} \frac{\partial^2 v}{\partial x_i \partial x_j} v \right| dx \quad (17) \end{aligned}$$

If we put:  $\tilde{v}_{ij} = e_{ij} v$ , then  $\tilde{v}_{ij} \in L^2(\Omega)$  and

$$\partial_{ik} \tilde{v}_{ik} = (\partial_{ik} \tilde{e}_{ik}) v + \tilde{e}_{ik} (\partial_{ik} v)$$

The hypothesis  $H_k$  and  $H_c$  gives that  $\tilde{v}_{ij}$  is an element of  $D_{Lt}$ . On the one hand, integration by parts gives us:

$$\sum_{i,j=1}^N \int_{\Omega} \left| \tilde{v}_{ij} \frac{\partial^2 v}{\partial x_i \partial x_j} v \right| dx \leq N \|\Delta \tilde{v}_{ij}\|_{L^2(\Omega)} \|\Delta u\|_{L^2(\Omega)} \quad (18)$$

On the other hand:

$$\|\Delta \tilde{v}_{ij}\|_{L^2(\Omega)} \leq 2CN \|\Delta v\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \quad (19)$$

Which allows to deduce from (17); (18); and (19):

$$\left| \langle L_t(u), v \rangle \right| \leq B \|\Delta u\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)}$$

With

$$B = \sup_{i,j=1}^N \left| e_{ij} \right| N^2 + \sup_{i,j=1}^N \left| \tilde{e}_{ij} \right| N^2 + 2CN^2$$

Using the Poincarre inequality, we can conclude that:

$$B = N^2 [\sup_{i,j=1}^N \left| e_{ij} \right| + \sup_{i,j=1}^N \left| \tilde{e}_{ij} \right| + 2C]$$

**Remark 0.3.3** Constant:

$$B = \frac{2N^2}{c_0} \left[ M + \frac{k_2 c_2}{2c_0} + \frac{G}{c_0} \right] \quad (20)$$

is maximum. Where  $M$  is the constant related to the thermaic conductivity (Assumption  $H_k$ ), and  $c_0$  and  $c_1$  those given by  $H_c$ .

### 0.3.2 Case where $F_c(u) = 0$

We devote this part for the study of the problem:

$$(P_{e,L,N}) \begin{cases} \frac{\partial u}{\partial t} + L_t(u) = P_c(x, t) \\ u / \partial \Omega x IR^+ = 0 \\ u / \partial \Omega x \{0\} = u_0 \end{cases} \quad \text{in } \Omega x IR$$

Let  $a_0$  a bilinear form defined by:

$$a_0(t, u, v) = \sum_{i,j=1}^N \int_{\Omega} \tilde{e}_{ij} \frac{\partial u \partial v}{\partial x_i \partial x_j} dx + \sum_{i,j=1}^N \int_{\Omega} e_{ij} \frac{\partial u}{\partial x_i} dx \quad (21)$$

Then, if  $u$  is a solution of the problem  $(P_{e,L,N})$ , it will check the following variational formulation:

$$\frac{\partial}{\partial t} \langle u, v \rangle + a_0(t, u, v) = \langle P_c, v \rangle \quad \text{in } H^{-1}(\Omega)$$

for all  $v \in H_0^1(\Omega)$

**Proposition 0.3.4**  $a_0(t, \cdot, \cdot)$  satisfies the following two assertions:

1. There exists a constant  $M > 0$  such as:

$$\left| a_0(t, u, v) \right| \leq M \|u\|_{H_0^1(\Omega)} \|v\|_{H_0^1(\Omega)}$$

for all  $u$  and  $v \in H_0^1(\Omega)$

Which means that  $a_0$  is a continuous bilinear form.

2. Coersivity in the following sens: there exists two  $\varepsilon_1$  and  $\varepsilon_2 > 0$  such as:

$$a_0(t, u, u) + \varepsilon_1 \|u\|_{L^2(\Omega)}^2 \geq \varepsilon_2 \|u\|_{H_0^1(\Omega)}^2$$

Proof

The measurability of  $a_0$  is a consequence of the continuity of  $\tilde{e}_{ij}$ ;  $e_{ij}$ ,  $u$  and  $v$ .

1 Continuity:

Let  $u, v \in H_0^1(\Omega)$ , from (21) we have:

Poincarre inequality implise that:

$$a_0(t, u, v) \leq \sup_{i,j=1}^N \left| \tilde{e}_{ij} \right| N \|\nabla u\|_{L^2(\Omega)} \|\nabla v\|_{L^2(\Omega)} +$$

$$\sup_{i,j=1}^N \left| e_{ij} \right| N^2 \|\nabla u\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)}$$

Poincarre inequality implise that:

$$\left| a_0(t, u, v) \right| \leq A_0 \|\nabla u\|_{L^2(\Omega)} \|\nabla v\|_{L^2(\Omega)}$$

For

$$A_0 = 2N \sup_{i,j=1}^N \left( \left| \tilde{e}_{ij} \right|, \lambda_1 N \left| e_{ij} \right| \right)$$

Which gives:

$$|a_0(t, u, v)| \leq A_0 [\|\nabla u\|_{L^2(\Omega)} + \|u\|_{L^2(\Omega)}] [\|\nabla v\|_{L^2(\Omega)} + \|v\|_{L^2(\Omega)}]$$

That we have:

$$|a_0(t, u, v)| \leq A_0 \|u\|_{H_0^1(\Omega)} \|v\|_{H_0^1(\Omega)}$$

**Remark 0.3.5** Constant  $A_0$  is maximum .

2. Coersivity:

We decompose the form  $a_0(t; u; u)$  in the following way:

$$a_0(t, u, u) = a_0^1(t) + a_0^2(t)$$

Where:

$$a_0^1(t) = \sum_{i,j=1}^N \int_{\Omega} \tilde{e}_{ij} \frac{\partial u \partial v}{\partial x_i \partial x_j} dx$$

$$\text{and } a_0^2(t) = \sum_{i,j=1}^N \int_{\Omega} e_{ij} \frac{\partial u}{\partial x_i} u dx \quad (22)$$

-In one hand, integration by parts gives:

$$-a_0^2(t) \geq -\frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 \quad (23)$$

- In the other hand, we have to distinguish three situations:

If there is an isotropic condition, the tensor of thermic conductivity will be diagonal:  $e_{ij} = 0$  for  $i \neq j$ .

So that

$$a_0(t, u, u) \geq -\frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 +$$

$$\inf_{i,j=1}^N |\tilde{e}_{ij}| \|u\|_{H_0^1(\Omega)}^2$$

We choose:

$$\varepsilon_1 = \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \quad \text{and} \quad \varepsilon_2 = \inf_{i,j=1}^N |\tilde{e}_{ij}|$$

If the case of monotony condition according to all direction, which means:  $(u_i, u_j \geq 0)$

$$a_0(t, u, u) \geq -\frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 +$$

$$\inf_{i,j=1}^N |\tilde{e}_{ij}| \|u\|_{H_0^1(\Omega)}^2$$

Then we take:

$$\varepsilon_1 = \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \quad \text{and} \quad \varepsilon_2 = \inf_{i,j=1}^N |\tilde{e}_{ij}|$$

For the general case, we have:

$$a_0^1(t) \geq \inf_{i,j=1}^N |\tilde{e}_{ij}| \|u\|_{H_0^1(\Omega)}^2 +$$

$$2 \inf_{i,j=1}^N |\tilde{e}_{ij}| \sum_{1 \leq i < j \leq N} \int_{\Omega} \frac{\partial u \partial v}{\partial x_i \partial x_j} dx \quad (24)$$

Since:

$$2 \sum_{1 \leq i < j \leq N} \int_{\Omega} \frac{\partial u \partial v}{\partial x_i \partial x_j} dx \geq -\sum_{i=1}^N \int_{\Omega} \left( \frac{\partial u}{\partial x_i} \right)^2 dx \quad (25)$$

By (23) (24) and (25) we obtain:

$$a_0^1(t) \geq \inf_{i,j=1}^N |\tilde{e}_{ij}| \|u\|_{H_0^1(\Omega)}^2 + 2 \sum_{1 \leq i < j \leq N} \int_{\Omega} \frac{\partial u \partial v}{\partial x_i \partial x_j} dx$$

$$a_0^1(t) \geq \inf_{i,j=1}^N |\tilde{e}_{ij}| \|u\|_{H_0^1(\Omega)}^2 - \inf_{i,j=1}^N |\tilde{e}_{ij}| \sum_{i=1}^N \int_{\Omega} \left( \frac{\partial u}{\partial x_i} \right)^2 dx$$

Which gives that:  $a_0^1(t) \geq 0$

Then:

$$a_0(t, u, u) + \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 \geq 0$$

$$a_0(t, u, u) + \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 +$$

$$(1 - \beta) \|u\|_{H_0^1(\Omega)}^2 \geq \beta \|u\|_{H_0^1(\Omega)}^2$$

Where  $\beta$  is an arbitrary parameter, which verify:

$$0 < \beta < \frac{1}{2}$$

We obtain:

$$a_0(t, u, u) + \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \|u\|_{L^2(\Omega)}^2 \geq (1 + 2\beta) \|u\|_{H_0^1(\Omega)}^2$$

Then we take:

$$\varepsilon_1 = \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \quad \text{and} \quad \varepsilon_2 = 1 + 2\beta \quad \text{for } 0 < \beta < \frac{1}{2}$$

If we choose:  $\varepsilon_1$  and  $\varepsilon_2$  such as:

$$\varepsilon_1 = \frac{N}{2} \sup_{i,j=1}^N \left\| \frac{\partial e_{ij}}{\partial x_i} \right\|_{L^\infty} \quad \text{and}$$

$$\varepsilon_2 = \sup(1 + 2\beta, \inf_{i,j=1}^N |\tilde{e}_{ij}|) \quad (\beta \in ]0, \frac{1}{2}[)$$

we have coersivity for all cases.

**Theorem 0.3.6** The problem  $(P_{e,L,N})$  admits a unique global solution.

**Proof**

Using proposition 0.3.4, we have continuety and coersivity of the bilinear form.

Thus theorem 1 and 2 of [4] make it possible to obtain the result.

### 0.3.3 General case

Now, we treat the problem  $(Pe)$  under the equivalent version  $(P_{e,L,\lambda})$

$$(P_{e,L,\lambda}) \left\{ \begin{array}{l} \frac{\partial u}{\partial t} + L_t(u) = \lambda F_c(u) + P_c \quad \text{in } \Omega \times IR \\ u / \partial \Omega \times IR^+ = 0 \\ u / \partial \Omega \times \{0\} = u_0 \end{array} \right.$$

**Theorem 0.3.7** The problem  $(P_{e,L,\lambda})$  admits a unique global solution.

Proof of this theorem will need a whole of lemmas.

**Lemma 0.3.8** \*  $F_c$  checkes:

(a)  $F_c(x, t, u) \leq F_1 |u|$  almost every where in  $IR$ .

(b)  $\frac{\partial F_c(x, t, u)}{\partial u} + F_2 \geq 0$  almost every where in  $D_\infty$

(c) There exists  $\delta_0 > 0$  such that:

$$e^{-\delta} F_c(x, t, e^{\delta} u) \in L^2(\Omega) \text{ for } \delta > \delta_0.$$

**Proof**

According to the properties checked by F, it is enough to take:

$$F_1 = \gamma_1 c_0^{-1} \text{ and } F_2 = \gamma_2 c_0^{-1}$$

which prove the first and second points of the lemma.

Let  $u$  element of :  $H_0^1(\Omega)$  then  $e^{\delta} u \in H_0^1(\Omega)$

Thus

$$|F_c(x, t, e^{\delta} u)| \leq c |e^{\delta} u|$$

That implies:

$$e^{-\delta} F_c(x, t, e^{\delta} u) \in L^2(\Omega)$$

**Definition 0.3.9** An operator  $T$  is known as monotonous in J.Lions sens if :

$$\langle Tv - Tw, v - w \rangle \geq 0 \text{ for all } v, w \text{ in } H_0^1(\Omega)$$

In the following, we take:

$$\tilde{u} = e^{-\delta} u$$

We obtain:

$$L_t(\tilde{u}) = e^{-\delta} L_t(u)$$

and then:

$$\frac{\partial \tilde{u}}{\partial t} + \partial \tilde{u} + L_t(\tilde{u}) = \lambda e^{-\delta} F(x, t, e^{\delta} \tilde{u}) + e^{\delta} P_c$$

Let's put:

$$F_1(x, t, \tilde{u}) = F_c(x, t, e^{\delta} \tilde{u})$$

Thus  $u$  solution of a problem  $(P_{e,L,\lambda})$  if and only if  $u$  checks:

$$\frac{\partial \tilde{u}}{\partial t} + \partial \tilde{u} + L_t(\tilde{u}) = \lambda e^{-\delta} F_c(x, t, e^{\delta} \tilde{u}) + e^{-\delta} P_c$$

Let  $b_0$  be defined by:

$$b_0(t, v, w) =$$

$$\delta \int_{\Omega} v w dx + a_0(t, v - w, v - w) - \lambda e^{-\delta} \int_{\Omega} (F_1(x, t, v) w) dx$$

We consider the variationel problem defined by:

$$\frac{\partial}{\partial t} \langle u, v \rangle + b_0(t, u, v) = \langle e^{-\delta} P_c, v \rangle$$

Then we define the operator  $b_1$  by:

$$\langle b_1(t)u, v \rangle = b_0(t, u, v)$$

**Lemma 0.3.10** The operator  $b_1(t)$  depends mesurably on  $t$ , and is hemi-continous.

**Proof**

We must show that:

For any sequence  $t_n \rightarrow 0$  we have  $b_1(t_n) \rightarrow b_1(0)$

Indeed,

$$\langle b_1(t_n)u, v \rangle = b_0(t_n, u, v)$$

$$= \delta \int_{\Omega} v w dx + a_0(t_n, v, w) - \lambda e^{-\delta} \int_{\Omega} F_1(x, t_n, v) w dx$$

Proprieties of  $a_0(t, u, v)$  and  $F$  permet to conclude.

**Proposition 0.3.11** It exists  $\delta_0^*$  such that, for all  $0 < \delta < \delta_0^*$ ; is monotonous.

**Proof**

While posing

$$B = \langle b_1(t)v - b_1w, v - w \rangle$$

Thus

$$B = \delta \int_{\Omega} (v - w)^2 dx - \lambda e^{-\delta} \int_{\Omega} (F_1(x, t, v) - F_1(x, t, w))(v - w) dx + a_0(t, v - w, v - w)$$

What implies:

$$B \geq \delta \|u\|_{L^2(\Omega)}^2 - \varepsilon_1 \|v - w\|_{L^2(\Omega)}^2 - \varepsilon_2 \|v - w\|_{H_0^1(\Omega)}^2 - \lambda F_2 \|v - w\|_{L^2(\Omega)}^2$$

Let us choose for example:

$$\delta_0^* = \varepsilon_1 + \lambda F_2$$

**Proposition 0.3.12 I :** It exists  $\tilde{\varepsilon} > 0$  such as :

$$\langle b_1(t)u, u \rangle \geq \tilde{\varepsilon} \|u\|^2$$

For all:  $\varepsilon < \tilde{\varepsilon}$

**Proof**

We have:

$$\langle b_1(t)u, u \rangle =$$

$$\delta \int_{\Omega} u^2 dx + a_0(u, u, t) - \lambda e^{-M} \int_{\Omega} F_1(x, t, u) u dx \geq \delta \|u\|_{L^2(\Omega)}^2 + \varepsilon_2 \|u\|_{H_0^1(\Omega)}^2 - \varepsilon_1 \|u\|_{L^2(\Omega)}^2 - \lambda F_2 \|u\|_{L^2(\Omega)}^2$$

The previous result gives:

$$\langle b_1(u), u \rangle \geq (\delta - \varepsilon_1 - \lambda F_2) \|u\|_{L^2(\Omega)}^2 + \varepsilon_2 \|u\|_{H_0^1(\Omega)}^2$$

Let

$$\varepsilon^* = \delta - \varepsilon_1 - \lambda F_2$$

We obtain:

$$\langle b_1(u), u \rangle \geq \varepsilon^* \|u\|_{L^2(\Omega)}^2 + \varepsilon_2 \|u\|_{H_0^1(\Omega)}^2$$

If we choose:  $\tilde{\varepsilon} = \inf(\varepsilon_1^*, \varepsilon_2)$

We obtain the result.

**Proof of theorem**

**Lemma 0.3.9** propositions 0.3.10, 0.3.11 and theorem 1, 2, and 3 of [4] give the theorem **0:3:6**.

**Remark 0.3.13** For reasons of compatibility between **lemma 0.3.7** and proposition 0.3.10, we will choose:

$\delta_0 < \delta_0^*$ . Indeed, it is enough to choose  $\delta_0 = \varepsilon_1$  and in this case:

$$\delta_0 = \varepsilon_1 < \delta < \delta_0^* = \varepsilon_1 + \lambda F_2$$

Where  $\lambda F_2 \neq 0$  and in this case, we have  $\delta \in ]\varepsilon_1, \varepsilon_1 + \lambda F_2[$

**Conclusion:**

In this paper, we obtained the theorem 0.4.6 by two steps. In the first time, we have studied the linear case by constructing the operator  $L_t$  and natural assumptions ( thermophysical nature of the data). For the nonlinear case, we exploited a variationnal formulation and application of the results of D.L for obtaining the existence and unicity.

In a future work, we hope to obtain the same result with dependence not only of space and time but also of the thermal field.

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